MARK SCHEME for the October/November 2013 series

0445 DESIGN AND TECHNOLOGY

0445/43

Paper 4 (Systems and Control), maximum raw mark 50

This mark scheme is published as an aid to teachers and candidates, to indicate the requirements of the examination. It shows the basis on which Examiners were instructed to award marks. It does not indicate the details of the discussions that took place at an Examiners' meeting before marking began, which would have considered the acceptability of alternative answers.

Mark schemes should be read in conjunction with the question paper and the Principal Examiner Report for Teachers.

Cambridge will not enter into discussions about these mark schemes.

Cambridge is publishing the mark schemes for the October/November 2013 series for most IGCSE, GCE Advanced Level and Advanced Subsidiary Level components and some Ordinary Level components.



	Pa	ge 2	Mark Scheme	Syllabus	Paper
			IGCSE – October/November 2013	0445	43
			Section A		
1	(a)	Torsion	Torque		[1]
	(1-)	Chasn			[4]
	(D)	Shear			[1]
	(c)	Factor of	f safety could be increased by:		
			larger gauge screws y of wall plugs		
		 using 	hardened screws		
			more screws spread across the frame. washers under screw heads		
			ion including two of above points, 2 marks.		
		Allow 2 r	narks if one point well described/justified.		[2]
2			shell structure – nut shells, eggs, honeycomb, shells tured shell structure – drinks cartons/cans, car bodi		[1] [1]
		Manulac		63.	[']
3		Any thire	l order lever, effort between load and pivot [1], label	[1].	[2]
-		,	· · · · · · · · · · · · · · · · · · ·		
4		Card sho	own folded or fold lines marked [1], capable of supp	orting a load [1].	[2]
5			top of hook [1]		
			the guy rope for tension [1] shear legs for compression [1]		
			ision in the rope holding the load.		[2]
6	(a)	A – spur	gear [1], allow 'gear' or similar. ${\boldsymbol B}-{\sf Worm}$ gear, [1]		[2]
	(b)	Reductio	on ratio is 48:1 . No mark for 1:48.		[1]
7	(a)		haft converts rotary motion to reciprocating motio haft converts reciprocating motion to rotary motio		[0]
		A CIAINS	mail converts reciprocating motion to rotary motio		[2]
	(h)	A cam w	ill convert rotary motion to reciprocating motion.		[1]
	(0)		in converticulty metion to recipiocating metion.		[,]
8	(a)	Colour c	odes are used because:		
	. /	• comp	onents are physically very small; it would be difficul		
		-	an be read regardless of the orientation of the com y other valid response.		[1]
	(b)	560 K co	lour code is green – blue – yellow . 2 × 1 marks		[2]

	Page 3	Mark	Scheme	Syllabus	Paper
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9	Connect	ions to NC [1] and C [1]	NC/		[2]

10 0.1 µF 100 nF, 2 marks, no marks for any other combination.

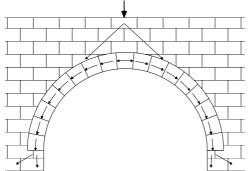
[Total: 25]

[2]

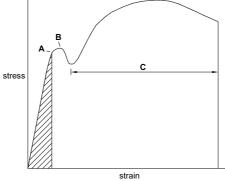
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Section B

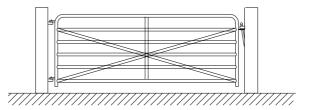
11 (a) Force through bricks distributed [1] Force through arch shown [1]



(b) (i) Strain gauge 1 will measure tension [1] Strain gauge 2 will measure compression [1] [2]
(ii) The markings are to allow accurate alignment of the strain gauge. [1]
(c) (i) Point A is elastic limit [1] allow mark for understanding shown. Point B is upper yield point, allow yield point [1] Allow marks for understanding shown. [2]
(ii) Section indicated by C is area of plastic deformation. [1]
(iii) Single point on graph indicated [1]. Clear indication of area showed [1]. [2]



(d) (i) Triangulation used [1], Central support(s) to stop bending of horizontals [1] [2]



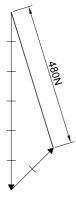
(ii) Indication of welding/bolts/rivets [1]

[1]

[2]

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(e) Resultant force **479.89 N**. Allow either calculation/triangle/parallelogram method. Suitable method chosen [1], accurate drawing/scale used [1] correct result [1].



- (f) Suitable joining method plates / scarf joint [1] Method of fixing shown screws / bolts / glue / wedges [1] Will keep two pieces in horizontal alignment [1] Will keep two pieces in vertical alignment [1]. 4 × 1 marks. [4]
- (g) (i) A moment is force × distance [1]. [1]
 (ii) Moments about A: Reaction at B x 9 = (3 x 900) + (7 x 500) [1] = (2700 + 3500) / 9 = 688.89 N [1] Reaction at A = 1400 - 688.89 = 711.11 N [1] [4]

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[Total: 25]
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[3]

[3]

- 12 (a) Examples of energy loss could include:
 - Heat transformer, charging battery, motor, gears
 - Sound motor, reduction gears, output shaft
 - Friction motor, reduction gears, output shaft
 - 3 × 1 marks for any three points included.

Type of energy involved must be given to gain each mark.

(b) Benefit of operating from batteries – Can be operated remotely, safer than mains power, no cables to get tangled, cause trip hazard.

 mark for any suitable benefit, reduced cost must be justified.
 Drawback – constant level of output from the transformer, battery output will decrease as charge drops or will fail suddenly. Battery output may be too low to operate the system. 1 mark for any suitable drawback.

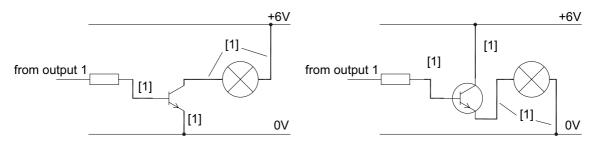
(c) (i) 1 mark for each correct direction arrow. (ii) Gear ratio is 3:1, gear C rotates at 20 rpm. (iii) Gear ratio is 3:1, gear C rotates at 20 rpm. (iii) Gear ratio is 3:1, gear C rotates at 20 rpm. (iii) Gear B, the idler gear can rotate freely [1], as it is not being driven by its shaft transferring drive to its shaft [1]. 2 marks for clear explanation. 1 mark for reference to free rotation being possible. (d) (i) Ratchet and pawl. (iii) Effort could be reduced by: Ensuring all parts are olied/greased and move freely Smaller pitch on the thread will reduce effort but require more turns Extending the lever used to operate the jack 2 × 1 marks. (e) (i) Benefit of: Ball race – reduced contact area, can resist thrust, easily replaced. Roller race – reduced contact area, will take greater radial load than ball bearing. Plain bearing. – low cost, can be pre oiled, can resist thrust. 3 × 1 marks, allow other valid benefits. (ii) A olyton bearing will be self lubricating, lower cost, easy to produce in bulk. (iii) Nylon has a relatively low melting point [1] and high speed rotation could melt bearing [1]. (f) (i) A bell crank lever will transfer motion through an angle, normally 90° [1]. Operated by wire for pulling action or rod for pushing action [1], 2 × 1 marks. (ii) Mechanical advantage will be gained by moving linkage to position B [1]. More movement of input link will be needed to move the output link the same distar as previously [1]	Page 6	Mark Scheme		Syllabus	Paper
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More movement of input link will be needed to move the output link the same distar as previously [1]	(f) (i)				ks. [2]
I tetoTI	(ii)	More movement of input link will be n			same distance [2]
[Iotal.]					[Total: 25]

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13	(a)	(i)	Silve	er [1] Brass [1] Tin [1], 3 × 1 marks.		[3]
	((ii)	Com	ponent containing a semiconductor could be transi	stor/diode/IC.	[1]
	(i	iii)	swite prob Res	anation should mention no moving mechanical ches are on one part, tactile action, lower cost the lem with arcing/oxidising of contacts. ponse with two points mentioned 2 marks. w 2 marks for a clear explanation of one point.		-
	(b)	(i)	Moto Whe	and NO contacts are joined each junction going to a or contacts are connected to common terminals of e on switch is operated the motor connections to powe w marks for understanding shown. 2 × 1 marks for a	ach switch [1]. er are reversed [1]	-
	((ii)	 C b M D at T¹ 	antages of relay circuit could be: connecting through a relay allows driver circuit volt e different. lotor circuit will run at higher current. river circuit and motor circuit are isolated so no in ffect the driver circuit. wo switches can be operated electronically by a sin ark for valid advantage.	nterference from	-
	(c)	(i)		s can differ in size, shape, intensity, angle of light Allow any other valid difference, 2 × 1 marks.	output, frequency	of light emitted [2]
	((ii)		- 1.8V = 4.2V [1] Substitution into formula R = V/I R 280 Ω [1] Correct answer with no working [3].	= 4.2 / .015 [1]	[3]
	(d)	(i)	Res	istance in the strain gauge will change.		[1]
	((ii)	Volta	RC and RB / strain gauge are potential dividers [1] age across the centre of each will change from 0 ge changes [1]. Voltmeter will measure change in vo		ce in the strain [3]

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(e) (i) AND gates [1], NOT gates or inverters [1].

- (ii) When switch 1 is pressed a logic 1 signal goes to AND gate A the other input is from NOT gate D which is a logic 1 signal, this makes the output of gate A logic 1 [1] As soon as gate A output has changed NOT gate C will send a logic 0 signal to an input of AND gate B preventing the gate from giving a logic 1 output [1]. Allow marks for understanding of each stage, 2 × 1 marks.
- (iii) Resistor to transistor base [1], emitter to 0 V [1], two lamp connections [1].
 3 × 1 marks for correct answer, any incorrect connections maximum of 2 marks. Emitter follower circuit can be used. [3]





[2]