

Cambridge International Examinations Cambridge International General Certificate of Secondary Education

DESIGN AND TECHNOLOGY

0445/43 May/June 2016

Paper 4 Systems and Control MARK SCHEME Maximum Mark: 50

Published

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				Cambrio	dge IGC	<u> SE – M</u>	lay/Jur	ne 201	6			0445		43
						Sec	ction A							
1	(a) /	A momer	nt is forc	e × dista	ance, tur	rning et	ffect or	force	whicl	n tries t	o cau	ise turning,	, 1 r	mark [1]
	(b)	(i) 3001	N , 1 mar	k										[1]
	(Í It wil	l remain	ill move t in equilil for unde	brium in [•]	that po	sition,	-						[2]
2	Cros	s braces	/ triangu	aces / tria ulation to ark. No v	prevent	side to	o side n	noverr	nent,	1 mark.		1 mark.		[3]
3	at reg A gla shatt The v the w Ment	gular inte ss plate ers the c width of t vidth. Cle	ervals or could be rack has he crack ar descr o differe	constant e glued to s got wid < could b ription of	tly to det o the sur er. e accura one of th	tect a w face of ately m hese m	videning f the be neasure nethods	g of th am ei ed e.g. s, 2 ma	e gap ther s . usin arks.	o. side of t g an ele	he cra ectroi	nce measu ack; if the g nic calliper detail, 1 ma	glas to r	s neasure
4		Belt Chai Direc	and pulle n drive ct gears ion drive	ferring dr ey, 'pulle e										[3]
		Loss Rota Only Char Char Slipp	of powe tion of m 1 mark nge in to nge in di ping can r in bear	rection o occur if a	h friction eed to dri increase f motion	iven sp and de	eed ca ecrease	n be a e of sp	beed		d			[2]
5	(a) ´	l mark fo	or one co	orrect, 2 i	marks fo	or 2 or 3	3 correc	ct.						
		Effort	R											

Load

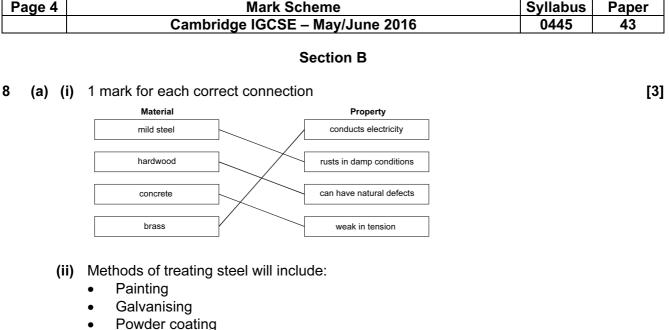
Fulcrum

Т

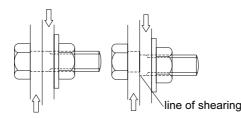
S

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(b) F	First order lever / 1st class lever, 1 mark.		[1
	Angle of output Forward voltage		
•	Frequency of light 3×1 marks		[3
Ċ	Electrolytic capacitor legs can be identified by a series of '–' or '+' symbolo covering and the cathode is shorter , no crimp around body of axial ver 2×1 marks		ody [2
1 ma	rk for each correct		
_			
dio	de (signal) LDR LED		
			[3

[Total: 25]



- Electroplating
- 2×1 marks for suitable methods.
- (iii) Bolt shown joining parts together, 1 mark.
 Indication of forces causing shear e.g. arrows, 1 mark.
 Clear indication of the effect of a shear force on the bolt, 1 mark.



- (b) (i) Reasons could include:
 - Strength to weight ratio when compared to solid beam
 - Resistance to torsion
 - Resistance to bending
 - Standard component
 - Accept lower cost, if qualified
 - 2×1 marks for suitable reasons.

(ii) Reasons for using concrete will include:

- Strong in compression, which is the main force that will be acting on the foundation
- Can easily be reinforced with steel bar to resist tension
- Can flow into difficult / intricate shapes
- Can be pumped into a foundation
- Relatively low cost as ballast is readily available in most area
- Will not degrade underground / long lasting

Detailed explanation including two points, 3 marks.

Detailed explanation of any one point, 2 marks. List of point with little explanation, 1 mark.

[3]

[2]

[3]

[2]

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(c) (A strut will resist compressive force, 1 mark. A tie will resist tensile force, 1 mark.		[2]
(i) 1 mark for each correct.		
	A gusset plate tie		[3]
(ii) Use of a suitable method of joining rafter to tie, 1 mark.		
("	Gusset plate attached securely, 1 mark. Clear annotation to sketches, 1 mark.		
(iv	Problems with using wood will include:		
	 Natural defects, e.g. knots, splits Insect damage Wet / dry rot Movement of the wood, warping / bending / twisting 2 × 1 marks 		[2]
(\	Static load is a non-moving load applied to a structure; a dynamic I quickly. Static load will include the loading caused by the parts of the items can be both static and dynamic e.g. vehicles at rest on a brid until they start to move, when they become dynamic. Description showing understanding of both types of load, 2 marks. Understanding of one type, 1 mark.	he structure	. Some
			[Total: 25]
			[]
9 (a) () Worm gear or worm wheel, 1 mark		[1]
(i	 Reasons for using a worm gear will include: High reduction ratio. Allow 'reduces the speed' Does not take up much room Can only operate in one direction (no slipping) Less frictional loss than a spur gear system Increased torque Turns drive through 90° Allow any other valid reason, 2 × 1 marks. 		[2]
			[4]
(ii	45:1 , 1 mark for values, 1 mark for correct way around.		[2]

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- (b) (i) The ring is magnetic, 1 mark and it will close the reed switch when directly underneath it, 1 mark. [2]
 - (ii) 1 mark for each column correct. Accept on / off, 1 / 0.

	instroked	moving / central	outstroked
reed switch 1	closed	open	open
reed switch 2	open	open	closed

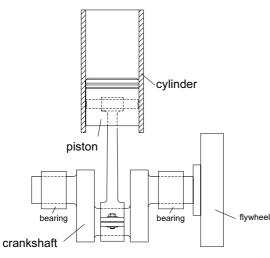
[3]

(iii) The reed switches give electronic feedback on the position of the piston, 1 mark.Reciprocating movement is converted into a (digital) electronic signal, 1 mark. [2]

(c)	(i)	 Safety precautions for compressed air will include: Pressure regulation Safety valve in the receiver tank Checks for corrosion in the receiver tank Allow other valid precautions, 1 mark. 	[1]
		 Safety precautions for mains electricity will include: Use of fuses / residual current device Visual inspection of wiring Isolation from damp / wet / explosive conditions Allow other valid precautions, 1 mark. 	[1]
	(ii)	 Benefits of wind power include: It is a renewable resource No pollution Allow other valid responses, 1 mark. 	[1]
		 Drawbacks include: Weather conditions are not always right for optimum performance Speed of device will need governing in high winds Allow other valid responses, 1 mark. 	[1]

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(d) (i) 1 mark for each item correctly identified.



[3]

[1]

		• •
(ii)	Reciprocating motion is converted to rotary motion.	[2]
(iii)	Two lubrication points, 1 mark each. Could be bearings, small end, big end, cylinder wall. Accept marking on either view of engine parts.	[2]
(iv)	Reasons for using a roller bearing include: Can take a high radial load, better than a ball bearing Will operate at high speed if well lubricated Can be sealed for life Longer lasting than a plain bearing	
	2 × 1 marks	[2]
		[Total: 25]

- 10 (a) (i) Description should include a graph to show that the astable is a regular square wave, 1 mark and has constant amplitude, 1 mark. [2]
 - (ii) A push to make switch will make contact when pressed, 1 mark, break contact when released, 1 mark. [2]
 - (iii) The multimeter dial should be set to Ω or continuity setting.



(iv) The reading should be less than 1Ω , 1 mark, allow buzzer may sound, 1 mark. [1]

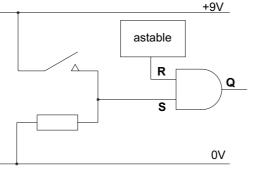
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(v) AND gate, 1 mark. Output column correct, 1 mark.

R	s	Q
0	0	0
0	1	0
1	0	0
1	1	1

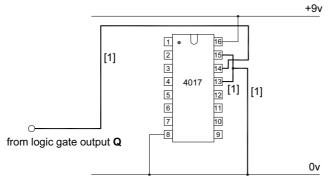
[2]

(vi) Resistor to 0V, 1 mark. Switch to +9V, 1 mark, Switch / resistor junction to S, 1 mark.



[3]

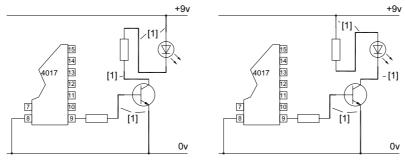
- (vii) Explanation should refer to the AND gate only passing on a signal when both inputs are high, 1 mark. When the switch is at 0 V there can be no signal passing through the gate, 1 mark.
- (b) (i) R1 + 2R2 = 21000, 1 mark. 21000 × 0.000001 = 0.021, 1 mark. 1.44 / 0.021 = 68.57 Hz, 1 mark. 3 marks for correct answer with no working. [3]
 - (ii) 1 mark for each connection correct, 3×1 marks.



[3]

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(c) Base and emitter connections correct, 1 mark. Collector to resistor or collector to LED, 1 mark. LED connected to +9V and resistor, 1 mark.



(d) The following stages will be needed: Cut the LED legs off close to the board, 1 mark. Heat up joint with soldering iron, 1 mark Use desoldering tool (solder sucker) or braid to remove the excess solder, 1 mark. Support circuit board above work surface so that the LED can be pushed out with soldering iron or pull with long nose pliers, 1 mark. Any three valid points, 3×1 marks.

[3]

[3]

[Total: 25]